

Distributed detection based on chronicle recognition

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Our context

- ◆ **Distributed systems:**
 - distributed process
 - distributed control and monitoring architecture
 - set of monitoring sites (*diagnosers*) with observers (M. Zanella): No consideration of overlapping between observers
- ◆ **Process failure detection**
- ◆ **On-line approach**
- ◆ **Model based approach**
- ◆ **Time model : chronicles**

The focus : communication aspects between diagnosers

- No assumptions on the message ordering
- No virtual global clock
- No loss of events
- **Problem of uncertainty due to the communication delays**
 - **clocks synchronisation** : stamping and reordering the messages
 - **specific algorithms for reordering of messages:**
 - need of a coordinator
 - no consideration of the duration between events occurrences

The objectives: an approach for....

- **The verification of timing and sequencing relationships between events**

To use for failure detection purposes

To improve classical techniques of clocks synchronisation and messages ordering

- **Addressing the problem of the cost related to the uncertainty**

by checking the membership of inter-events duration to specific intervals

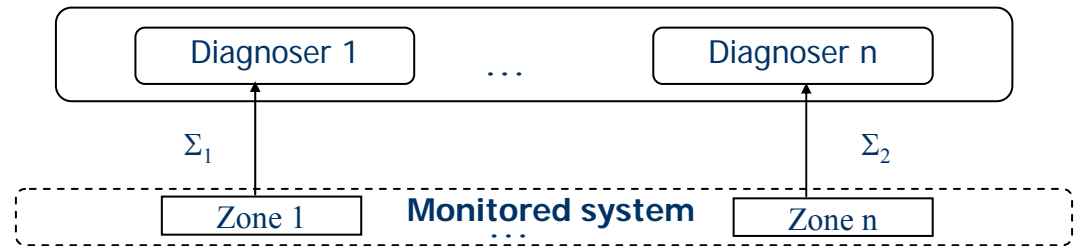
Time representation: the assumptions

- A **time stamp** can be assigned to each event
- Only **partial ordering** of events is known
- An **event** is characterized by its **occurrence date** and has no duration
- Timing information encoded in terms of **duration constraints**
- **Duration** : difference between the occurrence date of two events

Distributed detection and chronicle

- **Distributed process and distributed monitoring system**

- **The detection function** monitors the process evolution through chronicle recognition



- **Chronicle**: specific sequences of events related by timing constraints

- **Failure symptom detection**:

timing constraints of normal evolution: **constraint violation**

timing constraints of erroneous evolution: **constraint verification**

Preliminary notions

- **Event** : associated to the beginning/the end of an activity executed by the controlled process
- **Occurrence date**: date of an event
 - ✓ **local clock** associated to each diagnoser
- An event is dated in one and only one **local time referential** linked to one monitoring site

by The **occurrence function** noted **O** is defined by :

$$O : \Sigma \rightarrow Q^+$$

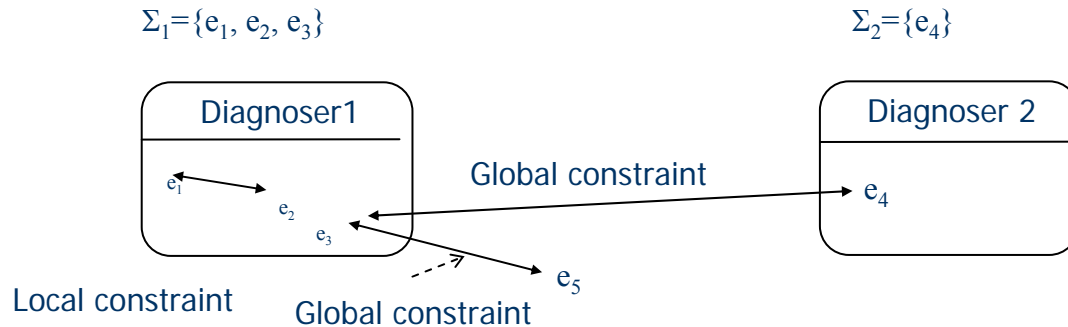
$$e_i \rightarrow O(e_i)$$

Preliminary notions

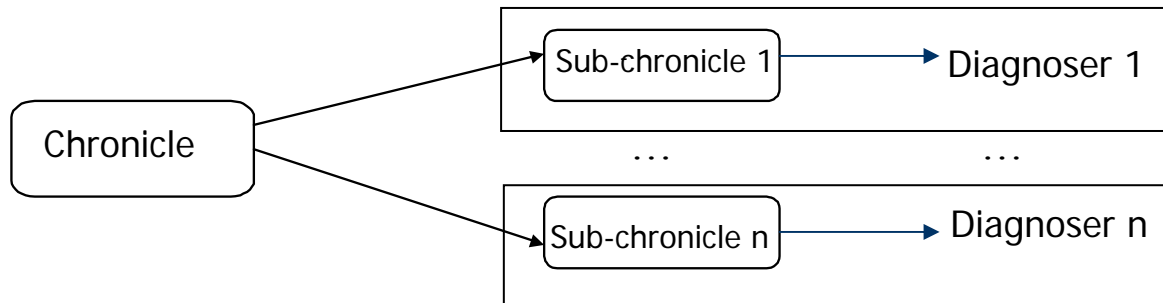
- **Constraints between events:** relationships expressed by a duration between events (causal relation of the application e.g. transport duration)
- Binary constraint:
 - **precedence type constraint** $O(e_i) < O(e_j)$
 - **interval type constraint** $d_{j,i} \leq O(e_j) - O(e_i) \leq f_{j,i}$ noted C_{ji}
avec $d_{j,i}$ et $f_{j,i} \in \mathbb{Q}^+$
- n-ary relation : **window admissibility constraint**
 $d_i \leq \min_j (O(e_j) - O(e_i)) \leq f_i$, noted D_i , with $d_i, f_i \in \mathbb{Q}^+$
- **Chronicle:** a set of events E and a set of timing constraints between these events

Preliminary notions

- **local constraints:** link events dated by a same diagnoser i
- **global constraints:** link events dated by different diagnosers



- notion of **sub-chronicle** : set of events, local constraints, global constraints



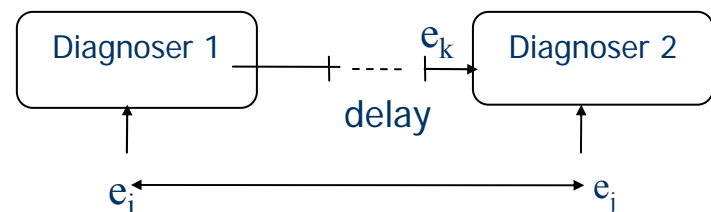
The distributed detection function

- **chronicle recognition:** checking that all the constraints are satisfied

⇒ recognition of the n sub-chronicles

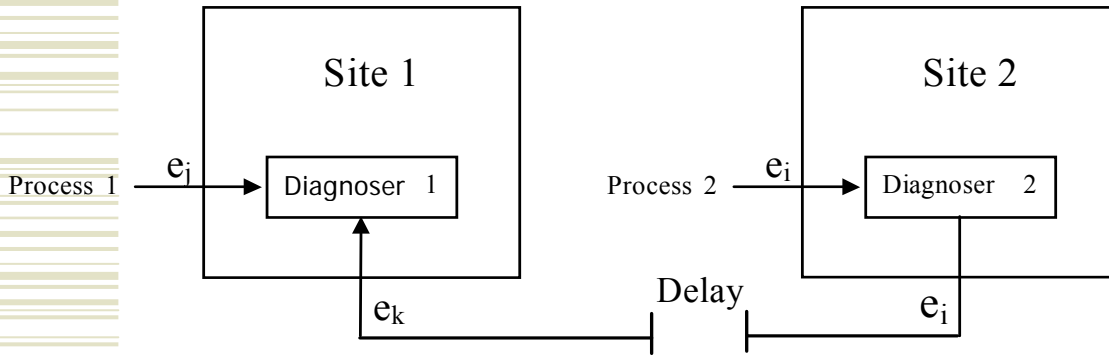
- **sub-chronicle:** set of events, local constraints, **global constraint**

⇒ How to verify a **global constraint with communication delay consideration?**



- **Hypothesis:** the possible values of the delay are uniformly distributed on the interval $[\delta_m, \delta_M]$

Global constraint verification



Problem:

$$d_{j,i} \leq O(e_j) - O(e_i) \leq f_{j,i}$$

$$\text{Delay } \Delta = [\delta_m \delta_M]$$

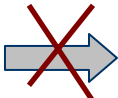
$$O(e_j), O(e_k)$$

O(e_i):
OK ?

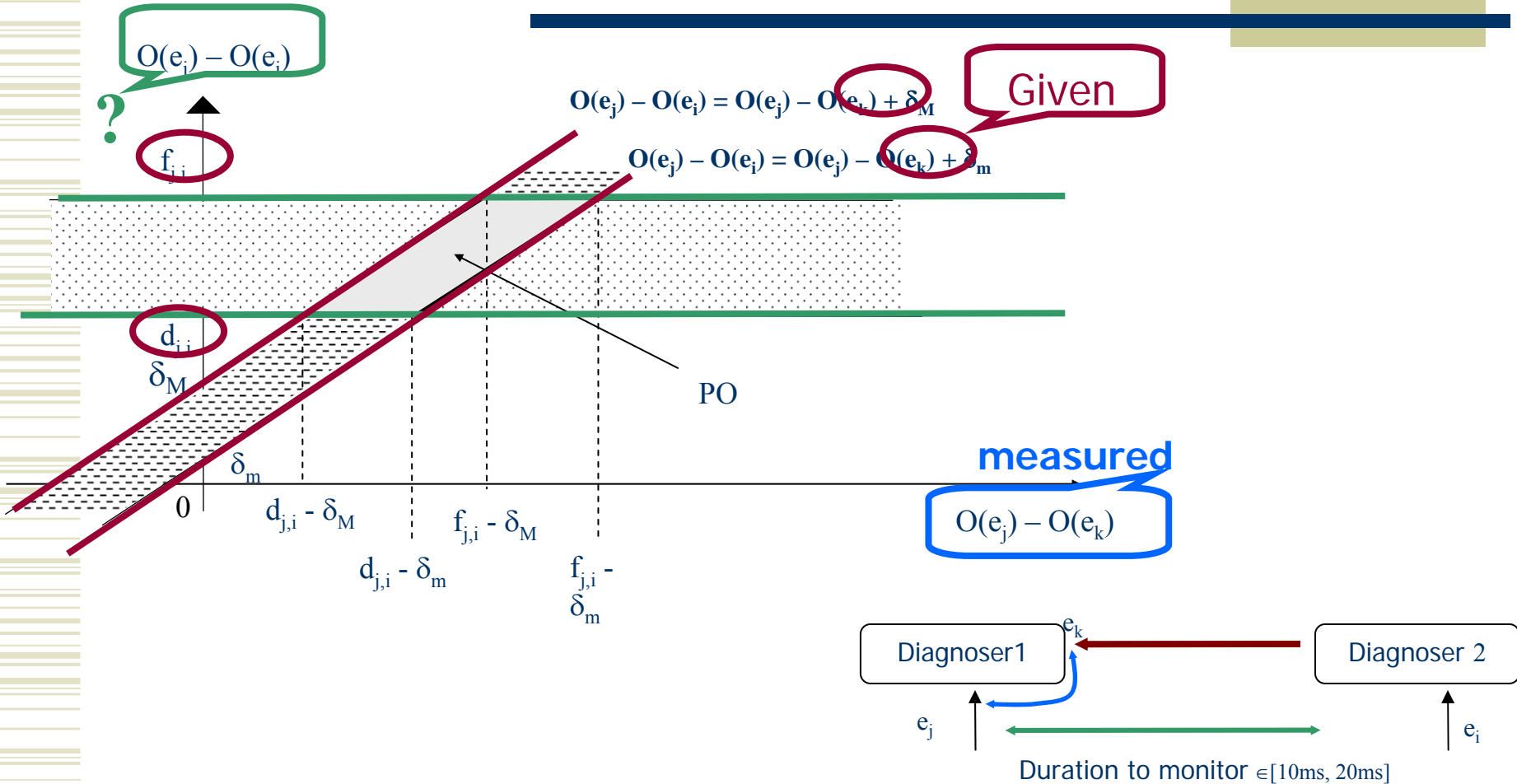
- A new formulation of the initial global constraint

$$O(e_j) - O(e_i) = (O(e_j) - O(e_k)) + \Delta = (O(e_j) - O(e_k)) + (O(e_k) - O(e_i)),$$

$$O(e_j) - O(e_k) + \delta_m \leq O(e_j) - O(e_i) \leq O(e_j) - O(e_k) + \delta_M \text{ (local constraint)}$$

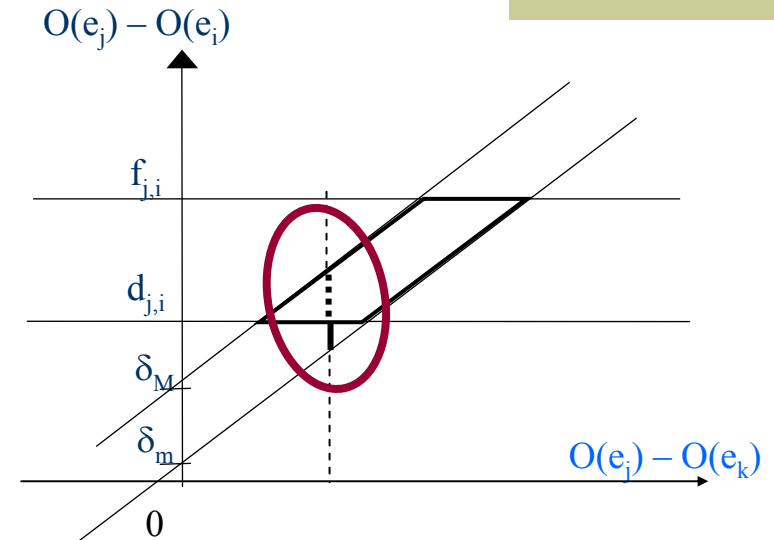
- Verification of a local constraint  verification of the global constraint

Global constraint verification

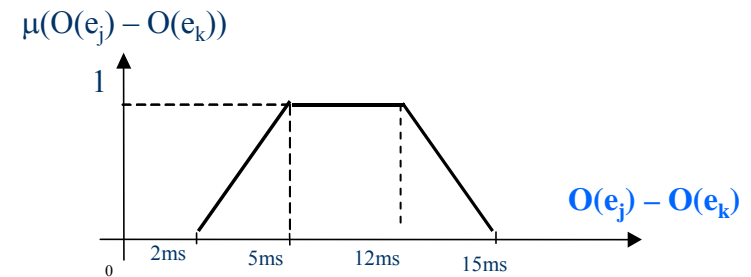
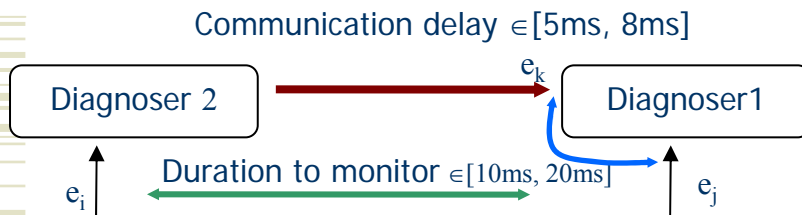


Global constraint verification

- **Quantify** among the set of possible durations $O(e_j) - O(e_i)$ / verify the specified constraint

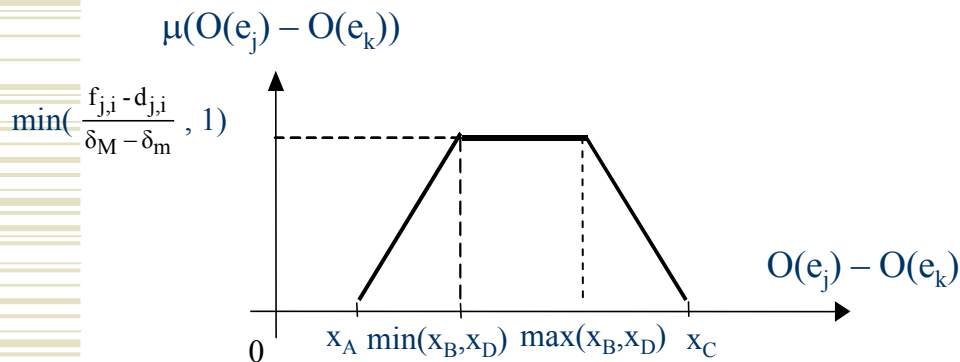


➔ Possibility function to check a constraint



Global constraint verification

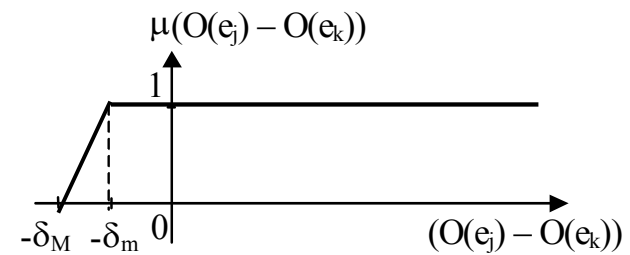
Interval type constraint



$$x_A = d_{j,i} - \delta_M, \quad x_B = d_{j,i} - \delta_m,$$

$$x_C = f_{j,i} - \delta_m, \quad x_D = f_{j,i} - \delta_M,$$

Precedence type constraint



Window admissibility type constraint :

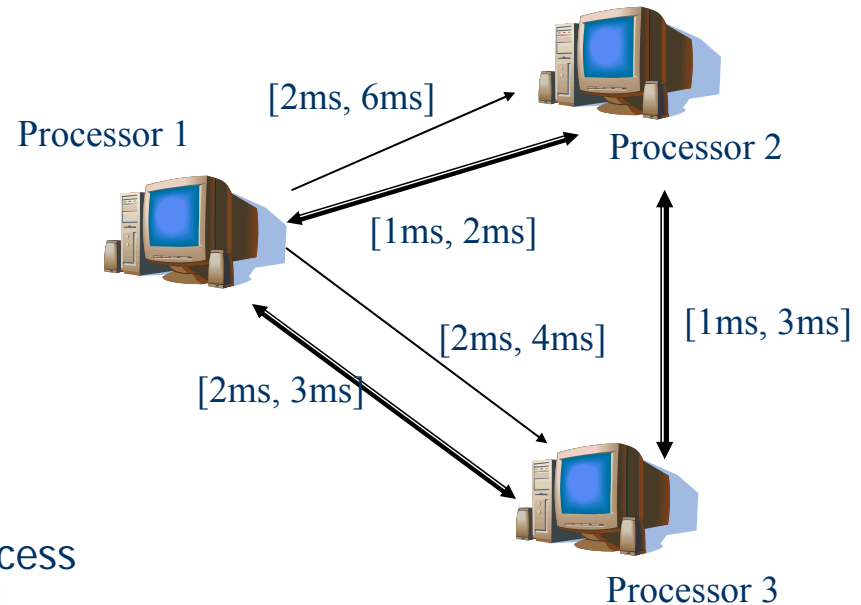
- Analogous result
- Conjunction of several interval constraints
- Problem of global order of events occurrences dated on different diagnosers to determine the last event

Tasks scheduling on multiprocessors architecture

- ◆ No tasks duplication
- ◆ 3 processors
- ◆ 3 tasks
- ◆ End of task i : event e_i
- ◆ The constraints:
 - Interval type
 - Global
 - Normal evolution of the process

$$C_{21} : d_{2,1} < O(e_2) - O(e_1) < f_{2,1}$$

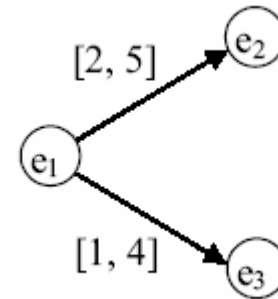
$$C_{31} : d_{3,1} < O(e_3) - O(e_1) < f_{3,1}$$



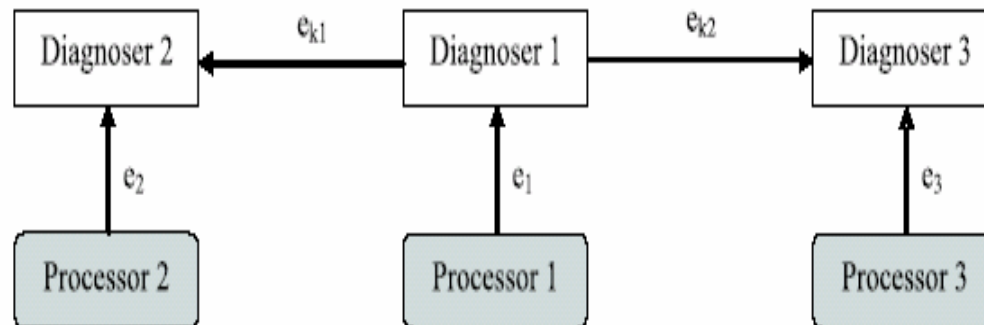
 Constraint bounds
 Communication delays

Tasks scheduling on multiprocessors architecture

- ◆ The chronicle (global model)
- ◆ The 2 sub-chronicles (local models)



- ◆ Monitoring architecture and message exchanges



Tasks scheduling on multiprocessors architecture

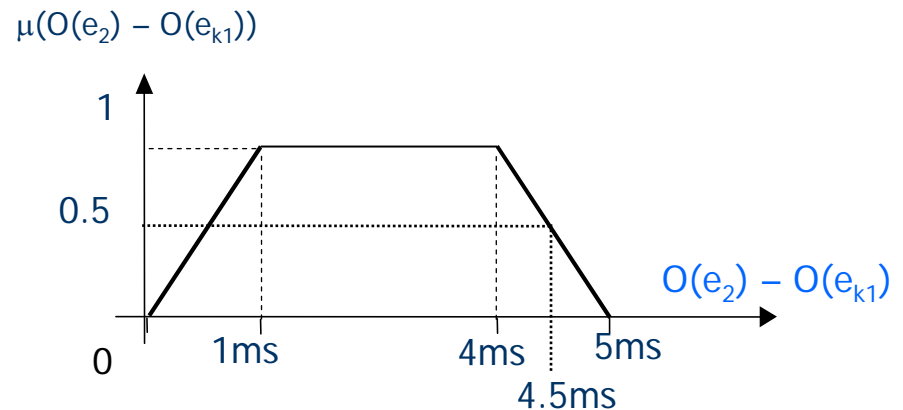
⇒ Monitoring of the duration between the end of task1 and the end of task2

$C_{21}: d_{2,1} < O(e_2) - O(e_1) < f_{2,1}$

with $d_{2,1} = 2\text{ms}$ and $f_{2,1} = 6\text{ms}$

$\Delta = [1\text{ms}, 2\text{ms}]$

Measure: $O(e_2) - O(e_{k1})$



$O(e_2) - O(e_{k1}) = 2.5\text{ms}$

→ No failure symptom detection

$O(e_2) - O(e_{k1}) = 5.5\text{ms}$

→ Failure symptom detection + localisation

$O(e_2) - O(e_{k1}) = 4.5\text{ms}$

→ **Possibility value: no certitude**

On the fuzzy notion....

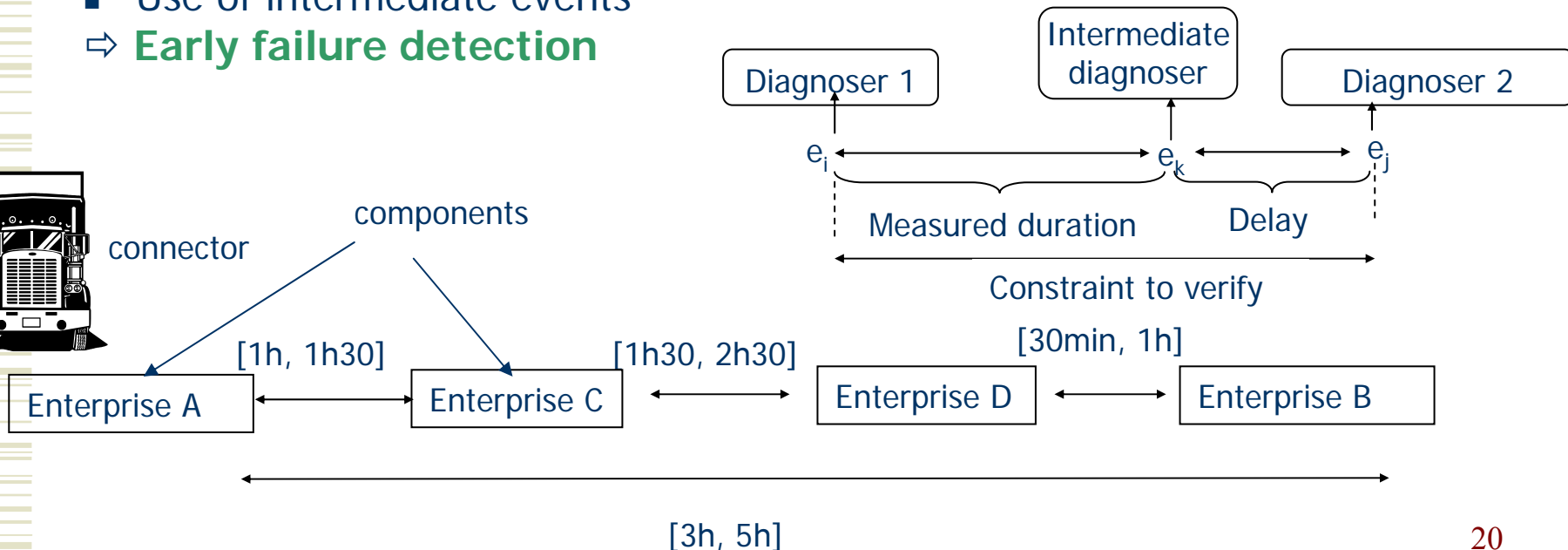
- How obtain a certitude on a global constraint verification?
 - Fix a verification threshold : how? Use of historical data
 - Ask an operator to check the process state (depends on the process type...)
 - Introduce a **cooperation between diagnosers**

Conclusion

- ◆ A monitoring architecture based on autonomous and cooperative sites: diagnosers
- ◆ Time model of the process evolutions: chronicle and sub-chronicles
- ◆ Communication delays consideration
- ◆ Possibility functions to verify a constraint
- ◆ Detection function: fuzzy verification of a timing constraint
- ◆ Suitable for systems / operational constraints are comparable to delays

Conclusion

- ◆ Application to computer network systems
 - ◆ Application to transportation systems or supply chains
 - Transportation delays between sites vs communication delays
 - Use of intermediate events
- ⇒ **Early failure detection**



Future Works

- To develop an approach to quantify the performance of the detection function according to the delay
- To consider delays with uncertain bounds or non uniformly distributed
- To integrate the detection function in a whole monitoring system and to consider others supervision and monitoring functions: **diagnosis** (localisation and explanations), recovery

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