





## Workshop on Measuring Assurance in Cyber Space

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A few comments about today's sessions


Paulo Veríssimo

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- take manageable bites out of the problem space
  - \*\*\* would suggest an overarching fault model to structure these reductions, i.e. how vulnerabilities, attacks, intrusions, develop, and their inter-relationship




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- Taxonomy:
  - attack-centric - identify attacks
  - defence-centric - manifestations, consequences
  
- \*\*\* as a matter of fact, i would say **cause-centric** and **consequence-centric**
- \*\*\* then, a structured fault model would help here, because what you are looking for is the last fault in the chain and/or the resulting error (not the primordial vulnerabilities, or the subsequent attacks)
- \*\*\* most taxonomies are devoted to faults and fault diagnosis, and maybe today we should be looking at taxonomies devoted to errors and error detection, or at least at ``**ultimate fault**'' diagnosis, if not at real error detection




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- security properties under a formal methods perspective describe them as invariants
  
- \*\*\* yes, as (logical) safety properties, but also as (**timeliness**) safety, and **liveness** properties

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- Adversary Work Factor - maximize the AWF to impart a system (cost of breaking in)
  - Critical Security Rating (CSR) - variables to give a numerical score to systems resilience to attack
  - \*\*\* merits of the objective:
    - may allow to establish a **contract** between the user and the provider of the system (Netscape SSL cost-of-breaking statement)
  - \*\*\* problems with the method:
    - **intrusiveness** of the intruder's operation analysis
    - **faithfulness** of red-teaming: completeness (you get existence proofs, you don't get non-existence proofs); truthfulness (the red team may not want to uncover some problems)
    - **cause-centric**

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- Even with diversity, independence is not believable. What you can hope is to quantify how reliable a diverse system will be.
  - \*\*\* on diversity in ID sensors, there is a difference between:
    - anomaly and misuse detection sensors
      - (the detection target is complementary)
    - sensors that measure different things
      - (only improve fault coverage in extension, not coverage of fault diagnosis/error detection itself)
    - diverse implementations of same class sensors
      - (improve coverage of fault diagnosis/error detection itself)



- Global probabilistic modeling of the system behaviour.
- E.g. a cause-centric attack model
  - fault diagnosis - estimate of P that more than  $f+1$  byz quorum attacked) (violation of assumptions)
- E.g. the consequence centric counterpart
  - Error detection - estimate of P that e.g. the agreement property is violated (violation of predicates)
- \*\*\* Comment:
- there must be separation of concerns between high-level functionality and underlying assumptions
- there should be a recursion of the above



- the match between vulnerabilities vis-a-vis attacks
- \*\*\* that's the way, but can't be blind, suggest research on vulnerabilities that are attackable, rather than attacked
- majority of vulnerabilities in applics
- \*\*\* yes, but the fact that they impair system functions blows the whistle on the runtime (e.g. OS), \*and\* on the SW architecture principles
- across OS vulnerabilities (vulner that span more than one OS)
- \*\*\* very relevant, as further input to some recent work on diverse-OS systems
- where to go from here?
- \*\*\* a structured fault model would help relating how chains of attack-vulnerability-intrusion develop, and evaluating the effect would approximate the analysis to the real \*risk\*



- fault prevention in OS
  
- \*\*\* cool, always a pleasure to see "good" OSs, but how effective?
  - this must be matched by an architectural approach to designing with trusted subsystems, otherwise it does not work, because appls will screw up anyway



## Conclusions

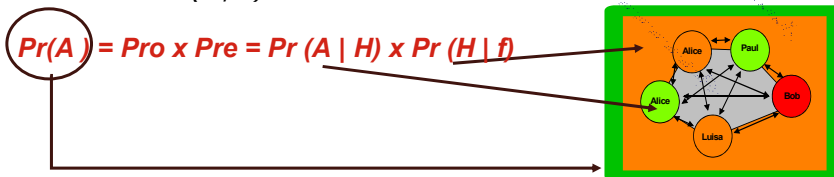
- missing link is often between precise and accurate specification and proof of properties, and (necessarily) imprecise and inaccurate specification and proof or estimation of the underlying environment assumptions
  
- \*\*\* guidelines:
- precision/accuracy of spec/proof of props
  - handle expressiveness and complexity (new properties; composition theorems, etc.)
- underlying environment
  - structured fault models, consequence-oriented (e.g. attack-vulner-intrusion lattices); adequate quantitative metrics
- link between high-level assertions and low-level runtime
  - separation of concerns;
  - trustworthiness(dependability)-aware assertions;
  - continuous (rather than discrete) notions of trust

## How might it be done?

- There will be several ways, certainly
- Our own thoughts in two slides
  
- Paper ref. can be found at
- [www.navigators.di.fc.ul.pt/it](http://www.navigators.di.fc.ul.pt/it)

## On coverage and separation of concerns

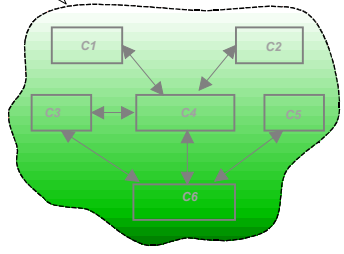
- **predicate P holds with a coverage Pr**
  - we say that we are confident that P has a probability Pr of holding
- **environmental assumption coverage (Pre)**
  - set of assumptions (H) about the environment where system will run
  - $Pre = Pr(H | f)$       *f- any fault*
- **operational assumption coverage (Pro)**
  - the assumptions about how the system/algorithm/mechanism proper (A) will run, under a given set of environmental assumptions
  - $Pro = Pr(A | H)$



# A robust design approach

Trustworthy C

- **Architectural hybridization:**
  - failure assumptions enforced by architecture and construction, thus substantiated
  - combined/recursive use of attack/vulnerability/intrusion prevention/removal/tolerance
- **Trusted (trustworthy) components:**
  - components or subsystems with justified coverage, used in the construction of fault-tolerant protocols under architectural hybrid failure assumptions



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